

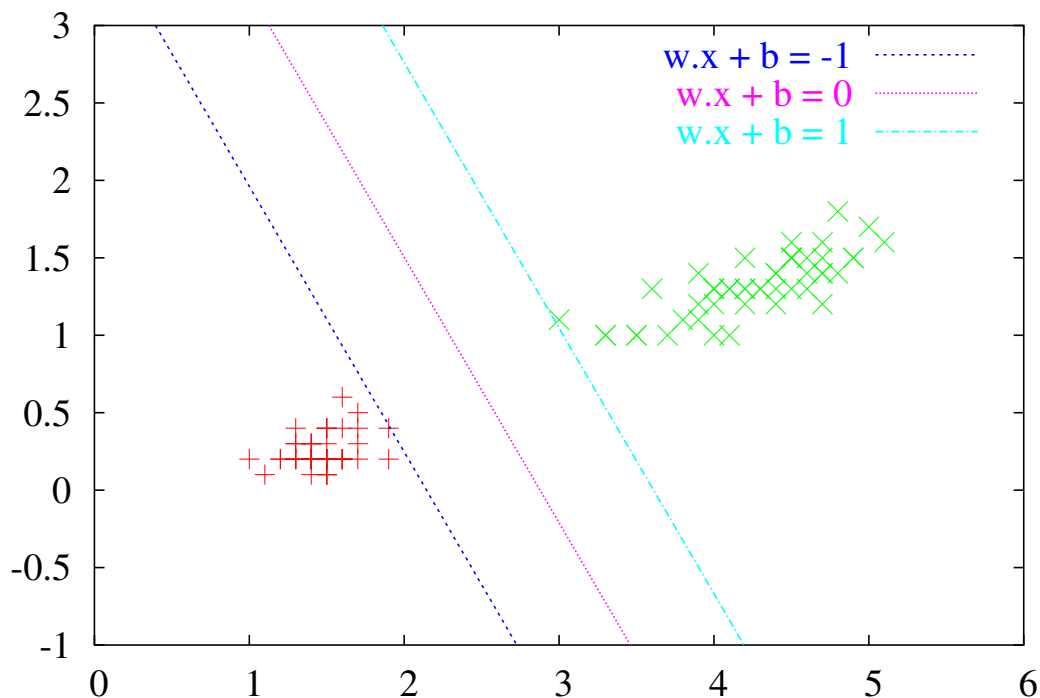
Learning Problem

Given training data $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_m, y_m)$, determine how to predict y for new inputs \mathbf{x} .

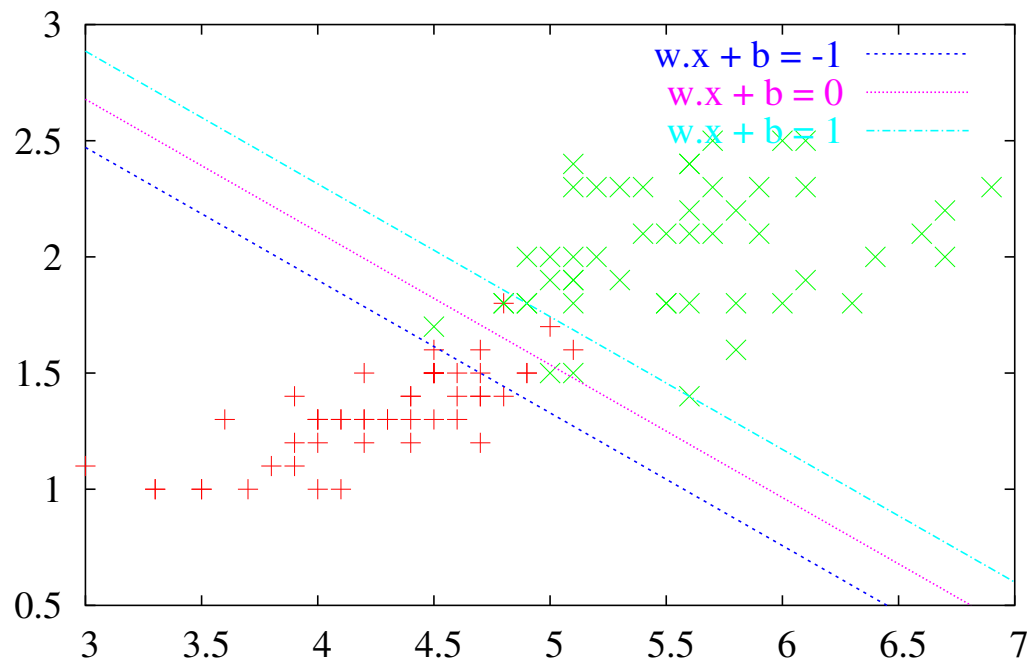
For binary classification, $y_i \in \{-1, 1\}$. For regression, $y \in \mathbf{R}$.

We assume that the prediction y for \mathbf{x} should be based on (\mathbf{x}_i, y_i) in the training data where \mathbf{x}_i is “similar” to \mathbf{x} .

Example SVM for Separable Examples



Example SVM for Nonseparable Examples



Support Vector Machines

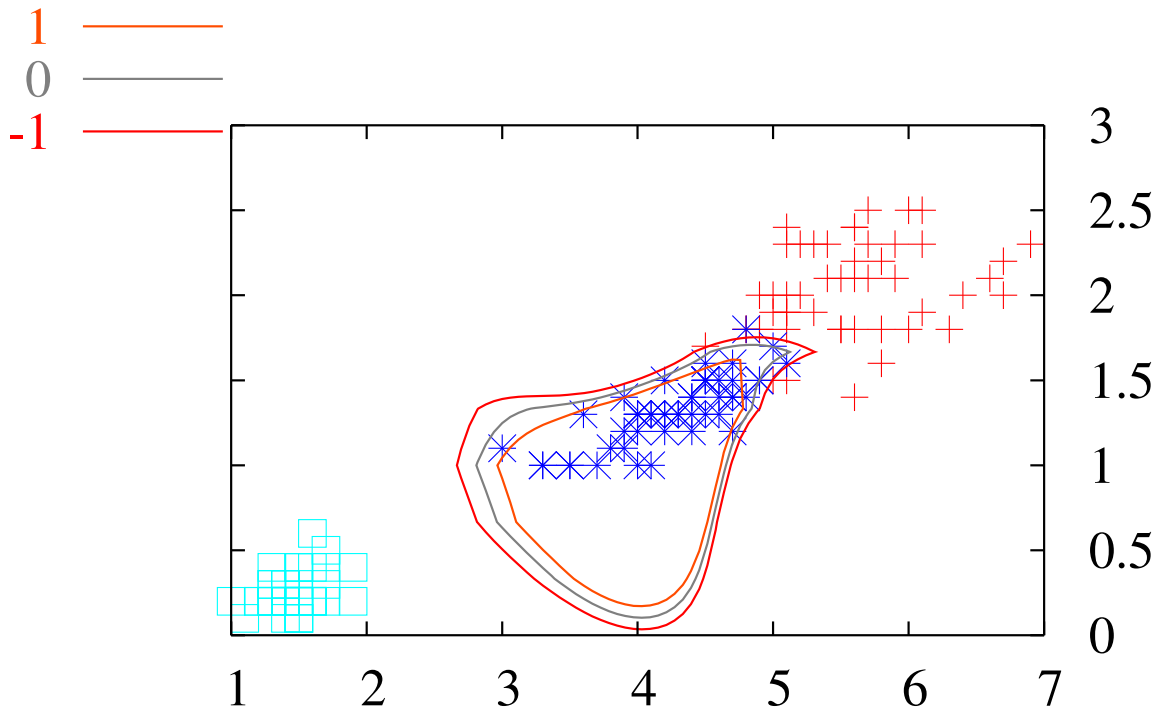
If possible, a SVM separates positive from negative exs. with a hyperplane (similar to perceptrons, adalines).

A SVM seeks to keep the weights as small as possible with positive exs. ≥ 1 and negative exs. ≤ -1 .

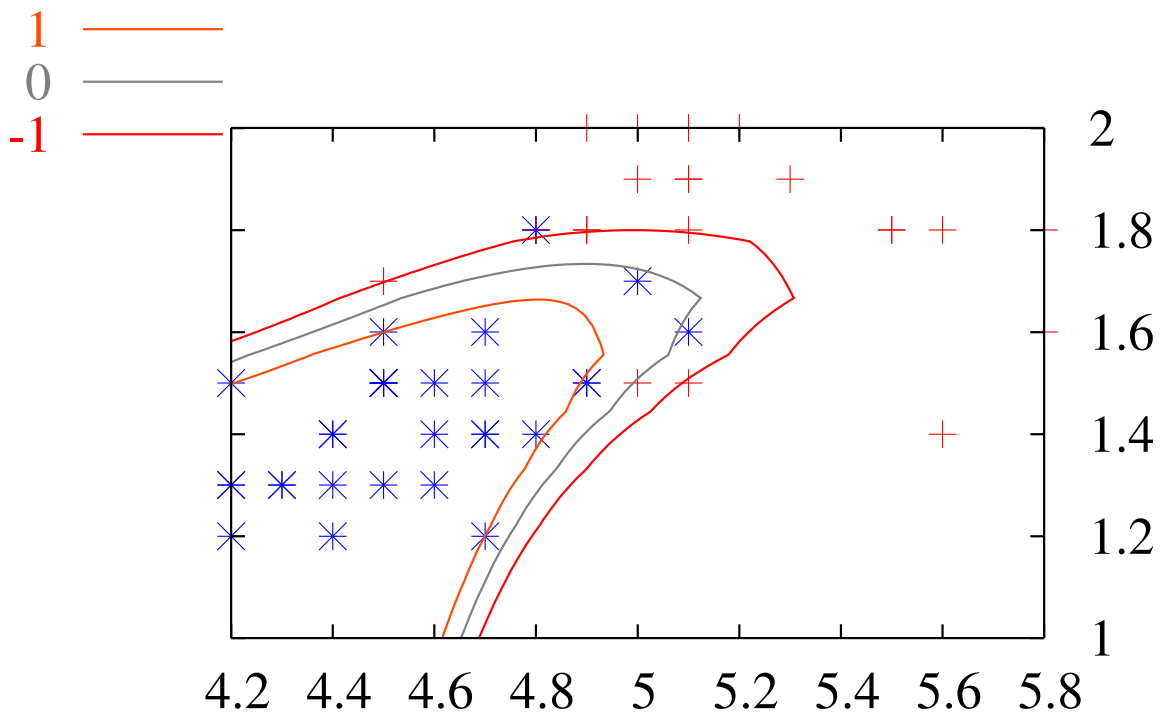
A SVM is defined by its support vectors, the positive exs. ≤ 1 and negative exs. ≥ -1 .

Kernel fns. allow nonlinear decision boundaries.

Example Gaussian Kernel SVM



Example Gaussian Kernel, Zoomed In



Kernel Functions

Let $(\mathbf{a} \cdot \mathbf{b})$ represent the dot product of vectors \mathbf{a} and \mathbf{b} , where $(\mathbf{a} \cdot \mathbf{b}) = \sum_j a_j b_j$.

Let Φ be a set of basis functions Φ_1, Φ_2, \dots . A *kernel function* $k(\mathbf{x}, \mathbf{x}') = (\Phi(\mathbf{x}) \cdot \Phi(\mathbf{x}'))$ is a way of measuring the similarity of two input vectors.

The “trick” of certain kernel functions is a simple computation that corresponds to a large number of basis functions.

Example Kernel Functions

Dot product: $(\mathbf{x} \cdot \mathbf{x}')$

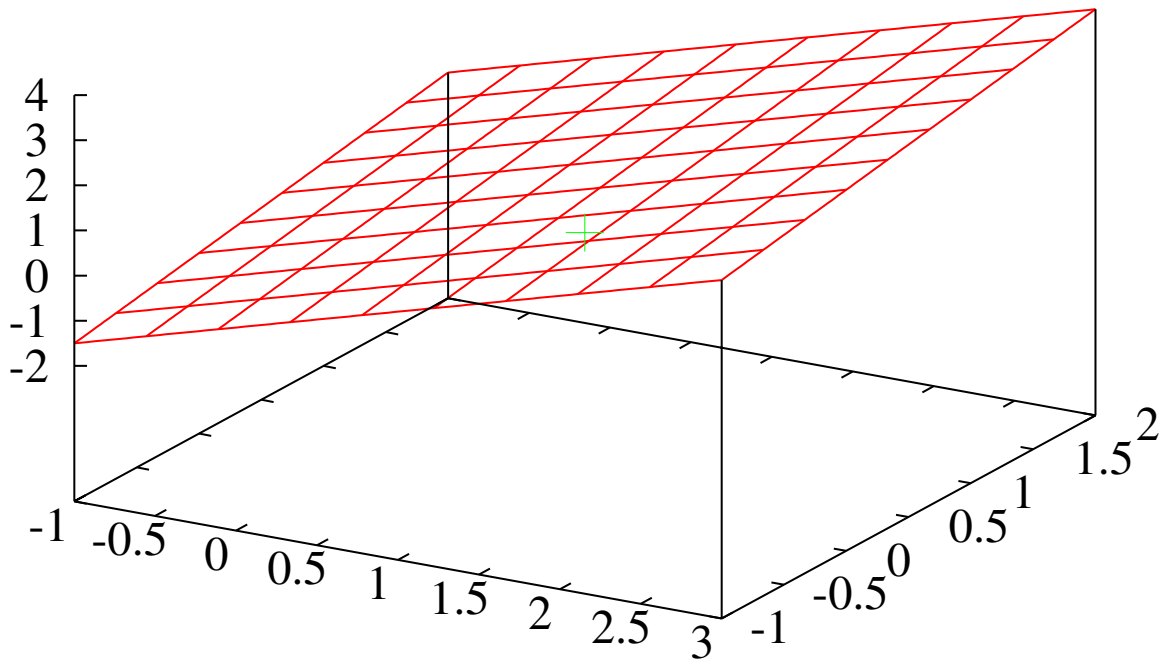
Polynomial: $(\mathbf{x} \cdot \mathbf{x}')^d$, where $d \in \{2, 3, \dots\}$
 $(a(\mathbf{x} \cdot \mathbf{x}') + c)^d$, where $d \in \{2, 3, \dots\}$, $a, c > 0$

Gaussian: $e^{-\|\mathbf{x} - \mathbf{x}'\|^2 / (2\sigma^2)}$, where $\sigma > 0$.

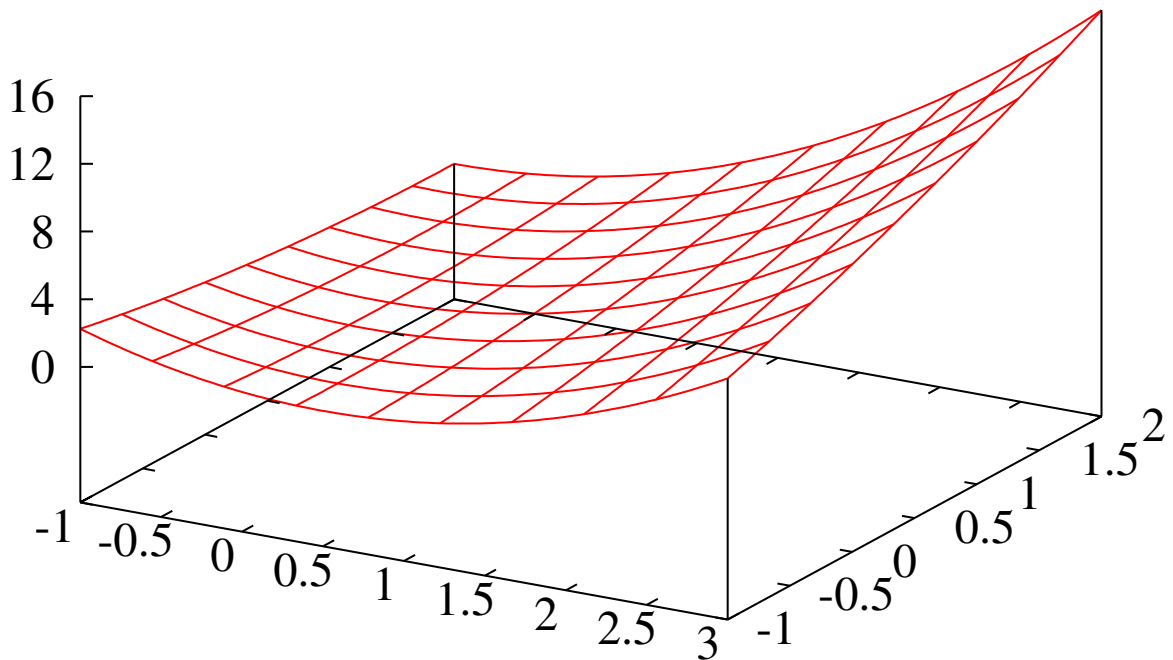
Hypertangent: $\tanh(\kappa(\mathbf{x} \cdot \mathbf{x}') + \theta)$, where $\kappa > 0$,
 $\theta \in \mathbf{R}$

The following figures illustrates these functions with one point fixed at $(1, 0.5)$.

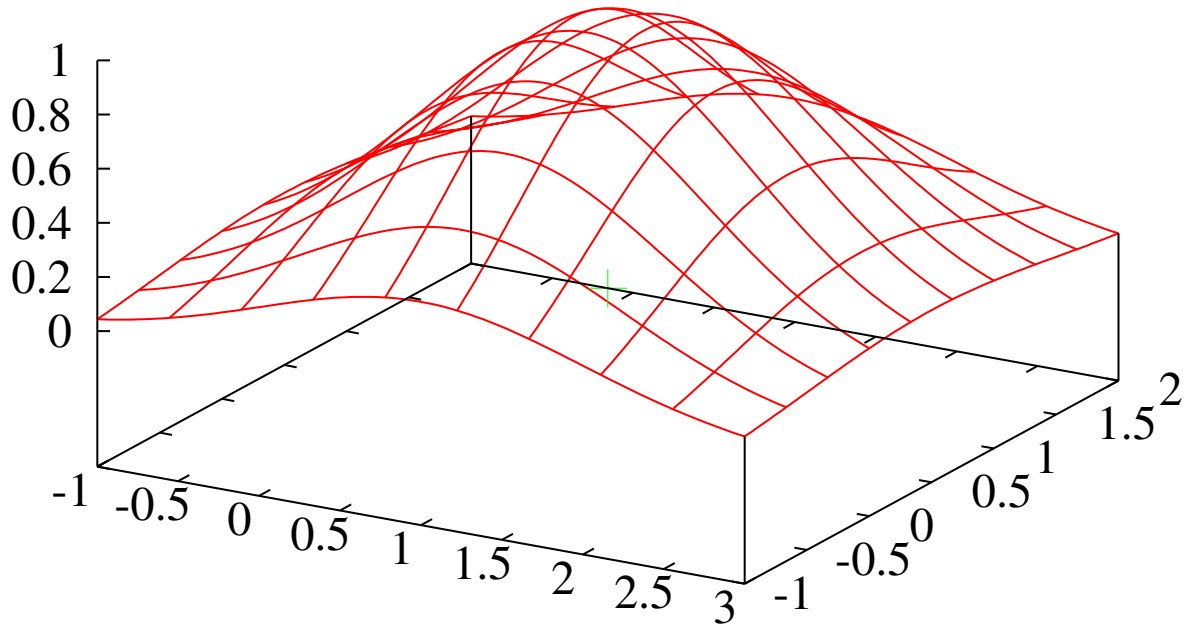
Dot Product



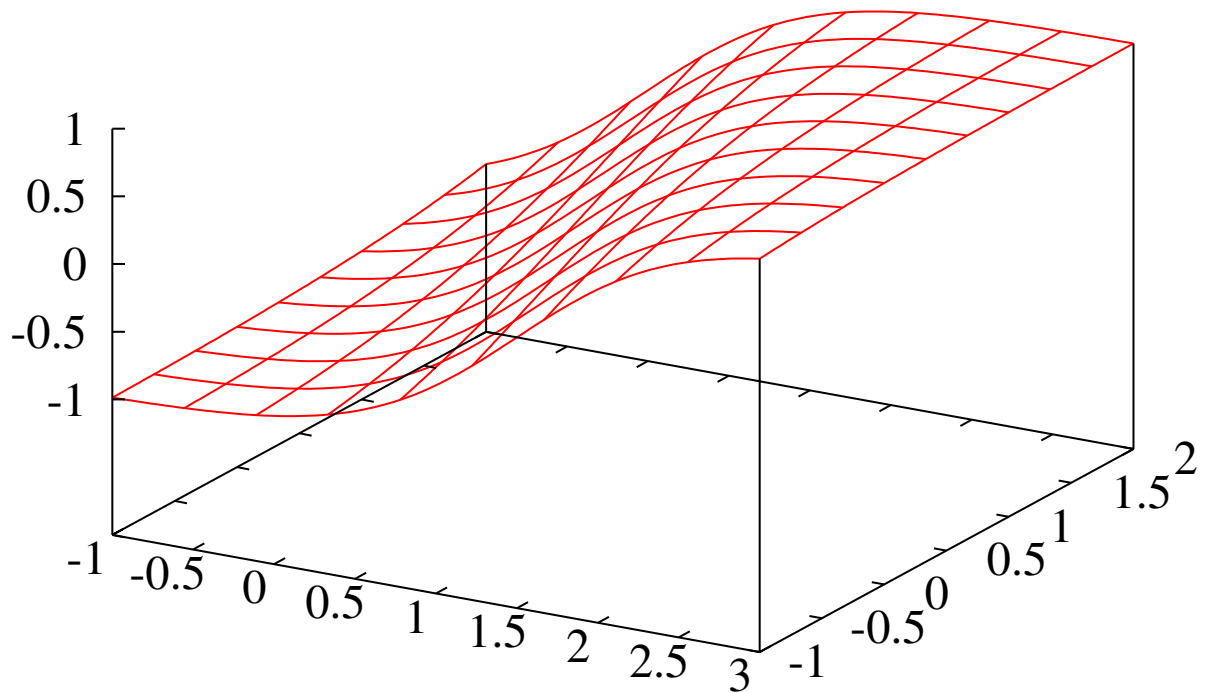
Polynomial, Degree 2



Gaussian



Hypertangent



Basis Functions

Except for \tanh , these functions have the form $k(\mathbf{x}, \mathbf{x}') = (\Phi(\mathbf{x}) \cdot \Phi(\mathbf{x}'))$. For example:

$$\begin{aligned} & ((u_1, u_2) \cdot (v_1, v_2))^2 \\ &= (u_1v_1 + u_2v_2)^2 \\ &= (u_1^2v_1^2 + 2u_1u_2v_1v_2 + u_2^2v_2^2) \\ &= (u_1^2, \sqrt{2}u_1u_2, u_2^2) \cdot (v_1^2, \sqrt{2}v_1v_2, v_2^2) \end{aligned}$$

Roughly, more basis functions implies richer representation, but more opportunities for overfitting. The Gaussian kernel corresponds to an infinite number of basis functions!
